Correlation function algebra for inhomogeneous fluids

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Abstract. We consider variational (density functional) models of fluids confined in parallel-plate geometries (with walls situated in the planes z=0 and z=L respectively) and focus on the structure of the pair correlation function $G(\mathbf{r}_1,\mathbf{r}_2)$. We show that for *local* variational models there exist two non-trivial identities relating both the transverse Fourier transform $G(z_\mu,z_\nu;q)$ and the zeroth moment $G_0(z_\mu,z_\nu)$ at different positions z_1,z_2 and z_3 . These relations form an algebra which severely restricts the possible form of the function $G_0(z_\mu,z_\nu)$. For the common situations in which the equilibrium one-body (magnetization/number density) profile $m_0(z)$ exhibits an odd or even reflection symmetry in the z=L/2 plane, the algebra simplifies considerably, and is used to relate the correlation function to the finite-size excess free energy $\gamma(L)$. We rederive non-trivial scaling expressions for the finite-size contribution to the free energy at bulk criticality and for systems where large-scale interfacial fluctuations are present. Extensions to non-planar geometries are also considered.

1. Introduction

In this paper we discuss the structure of correlation functions for fluids (or Ising-like magnets) adsorbed at walls and confined in parallel-plate (thin-film), cylindrical and spherical geometries. Such systems have been extensively studied in recent years to assess the influence that surface and finite-size effects have on bulk phase coexistence and criticality. Here we are not primarily interested in the phenomenology but seek rather to understand whether a central assumption crucial to a broad class of widely used variational (density functional) models has any consequences for the behaviour of the correlation function $G(r_1, r_2)$. Specifically, we shall show that for *local* functional models there exist very general relations which may be viewed as an algebra restricting the possible structure of $G(r_1, r_2)$. These turn out to be particularly powerful when the one-body (magnetization/density) profile has an odd/even reflection symmetry (as is often the case) and enable us to re-derive non-trivial scaling laws for the finite-size contribution to the free energy for systems close to the critical point [1, 2] or that have large-scale interfacial fluctuations [3, 4].

The starting point of our analysis is an appropriate variational model for the free energy. For almost all of our article we will consider grand potential-like functionals $\Omega[m(r)]$, where m(r) denotes the appropriate order parameter or local density variable. Thus for fluid systems m(r) corresponds to the number density although we shall adopt a magnetic notation and will often refer to m(r) as the local magnetization or spin density. The grand potential functional is written [5–7] as

$$\Omega[m(r)] = \mathcal{F}[m(r)] - \int m(r)h(r) dr$$
(1.1)

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where $\mathcal{F}[m(r)]$ is the Helmholtz free-energy functional and h(r) is the local magnetic field at point r. In a fluid context h(r) may be identified with $\mu - V_{\rm ext}(r)$ where μ is the chemical potential and $V_{\rm ext}(r)$ is the external field generated by the confining walls. Minimization of $\Omega[m(r)]$ with respect to magnetization configurations recovers the thermodynamic grand potential Ω [5–7]:

$$\Omega = \min \Omega[m(r)] = \Omega[m_0(r)] \tag{1.2}$$

where $m_0(r)$ is the equilibrium magnetization profile.

The connected correlation function $G(r_1, r_2)$ is defined in the usual way by

$$G(\mathbf{r}_1, \mathbf{r}_2) = \langle m(\mathbf{r}_1)m(\mathbf{r}_1)\rangle - \langle m(\mathbf{r}_1)\rangle \langle m(\mathbf{r}_2)\rangle \tag{1.3}$$

and satisfies the Ornstein–Zernike integral equation [5]

$$\int d\mathbf{r}' \ C(\mathbf{r}_1, \mathbf{r}') G(\mathbf{r}', \mathbf{r}_2) = \delta(\mathbf{r}_1 - \mathbf{r}_2)$$
(1.4)

where the direct correlation function $C(r_1, r_2)$ is defined by

$$C(r_1, r_2) = \frac{1}{k_B T} \frac{\delta^2 F[m(r)]}{\delta m(r_1) \, \delta m(r_2)}$$
(1.5)

and is evaluated at equilibrium.

One of the chief merits of the variational approach is the prescription for calculating $G(r_1, r_2)$ via the direct correlation function route embodied in (1.4) and (1.5). Often the fluid has a symmetry which makes the task simpler. For example, in planar parallel-plate geometries the one-body profile is a function of one coordinate, z say, and it is convenient to Fourier transform $G(r_1, r_2)$ and $C(r_1, r_2)$ with respect to the transverse displacement vector y_{12} of the two points r_1 and r_2 . Thus we define

$$G(z_1, z_2; q) = \int d\mathbf{y}_{12} \exp(i\mathbf{q} \cdot \mathbf{y}_{12}) G(\mathbf{r}_1, \mathbf{r}_2)$$

$$\tag{1.6}$$

and $C(z_1, z_2; q)$ similarly, which from (1.4) satisfy

$$\int dz_3 \ C(z_1, z_3; q) G(z_3, z_2; q) = \delta(z_1 - z_2). \tag{1.7}$$

We shall be particularly interested in the zeroth moment corresponding to q=0 and define (in standard notation)

$$G_0(z_1, z_2) \equiv G(z_1, z_2; 0).$$
 (1.8)

For the planar parallel-plate geometry the finite-size contribution to the grand potential Ω is conveniently measured by the surface excess quantity

$$\gamma(L) \equiv \frac{\Omega - \omega_b V}{A} \tag{1.9}$$

where $V \equiv AL$ is the volume of the thin film of width L and area A. Here ω_b is the bulk grand potential density. The quantity $\gamma(L)$ may be regarded as the finite-size-dependent surface tension (excess free energy per unit area) of the system. Differentiating with respect to L yields the solvation force [8]

$$f_s(L) \equiv -\frac{\partial \gamma(L)}{\partial L} \tag{1.10}$$

which is a useful measure of phase behaviour in the confined fluid. The most important conclusions of this paper concern the derivation of elegant relations between the correlation function $G_0(z_1, z_2)$ and (derivatives of) the free energy $\gamma(L)$.

Of course the exact density functional for non-trivial (interacting) three-dimensional systems is not known and approximate models must be considered for the purposes of calculation. The simplest approach (and one which has given invaluable insights into a number of problems [6]) is to assume that the Helmholtz functional is local so that we may write

$$\Omega[m(\mathbf{r})] = \int d\mathbf{y} \int_0^L d\mathbf{z} \left\{ \mathcal{L}^{(b)}(m(\mathbf{r}), \nabla m(\mathbf{r})) + \delta(\mathbf{z})\phi_1(m(\mathbf{r})) + \delta(\mathbf{z} - L)\phi_2(m(\mathbf{r})) \right\}$$
(1.11)

where $\mathcal{L}^{(b)}(m, \nabla m)$ is an appropriate bulk free-energy density while $\phi_i(m)$ models (short-ranged) interactions with the walls situated in the planes z = 0 and z = L, say. Most often $\mathcal{L}^{(b)}(m, \nabla m)$ is further approximated by a Landau expansion [6]

$$\mathcal{L}^{(b)}(m, \nabla m) = \frac{1}{2}(\nabla m)^2 + \frac{r}{2!}m^2 + \frac{u}{4!}m^4 - hm$$
 (1.12)

where, for fluid systems m must now be interpreted as the number density relative to the bulk critical value. The inadequacies of the Landau-type approach near the bulk critical temperature are well known, though more general expressions for $\mathcal{L}^{(b)}(m, \nabla m)$ can account for non-classical critical exponents in a phenomenological manner [9]. Such, generalized, local free-energy functionals have provided a profitable way of deriving critical exponent and scaling relations, although recently, it has been argued that local entropy-like functionals may well be better candidates for describing critical effects [10]. As well as being restricted to systems with short-ranged forces the local approximation is also inadequate for describing the pronounced oscillations in the density profile that occur when a high-density fluid is confined in a narrow geometry [6]. Nevertheless due to the continued widespread use of local functionals we believe that it is worth considering in detail what restrictions the local approximation places on the structure of correlation functions.

To address this question we borrow recent results and methods developed for analysing correlation functions at wetting transitions which have led to the introduction of coupled effective Hamiltonians [11–13]. While we shall not be particularly concerned with the wetting transition in this article, our analysis involves the further development and generalization of the stiffness-matrix formalism present in [12] and [13]. The essence of the method is to consider the properties of constrained functionals constructed by partial minimization of the grand potential functional $\Omega[m]$. The Ornstein–Zernike equation is then recast in a convenient matrix representation which allows us to exploit the separable properties of the constrained functionals. We emphasize here that the partial minimization procedure is exact in the present variational formalism and contrasts with the analogous result in the effective-Hamiltonian theory of wetting which arises due to a saddle-point approximation [14]. The present analysis also differs from the coupled effective Hamiltonian theory since it is necessary to consider the properties of constrained functionals of three (or more) collective coordinates rather than just two.

For the greater part of our article, embodying section 2 to section 5.2, we deal with planar inhomogeneous fluids described by local functionals of the form (1.11) but leave $\mathcal{L}^{(b)}$ and ϕ_i arbitrary. Our presentation is as follows: in section 2.1 we recall the basic strategy of the stiffness-matrix formalism considering constrained functionals of N collective coordinates and introducing the N(N+1)/2 structure factor matrix elements $S_{\mu\nu}(q)$ (with $1 \leq \mu, \nu \leq N$). Then in section 2.2 we show how the local character of $\Omega[m]$ necessarily leads to two sets of algebraic relations relating the $S_{\mu\nu}(q)$ and $S_{\mu\nu}(0)$ at any three planes z_1, z_2 and z_3 . This means that for arbitrary positions $z_1 \leq z_2 \leq z_3$ the zeroth moments $G_0(z_\mu, z_\nu)$ satisfy two non-trivial identities. We illustrate this in section 3 for the simplest

possible scenario corresponding to fluid adsorbed at a single wall before turning our attention to the much more interesting problem of fluids confined in a parallel-plate geometry. For this case, if we consider examples in which the equilibrium one-body profile exhibits a reflection symmetry in the z=L/2 plane, the algebra simplifies considerably. Even symmetry corresponds to profiles satisfying $m_0(z)=m_0(L-z)$ and occurs if the two confining walls are identical. For this case one of our relations readily rederives an exact result due to Henderson [15] valid for fluids (interacting with quite arbitrary interatomic forces) confined between perfectly hard walls. On the other hand, profiles satisfying $m_0(z)=-m_0(L-z)$ correspond to odd symmetry and occur in Ising-like systems with competing surface fields. Such geometries have attracted considerable attention in recent years (see [3, 4, 16, 17] for example and references therein) due to presence of strong interfacial finite-size effects and novel symmetry-breaking mechanisms.

For both even and odd systems the correlation function relations severely restrict the form of the zeroth moment and we are able to derive a very elegant expression for $G_0(z_1, z_2)$ in terms of $G_0(z_1, z_1)$, $G_0(z_2, z_2)$, $m_0'(z)$ and $\gamma(L)$. Using this approach we rederive nontrivial scaling laws at the bulk critical point and when large-scale interfacial fluctuations are present in the confining geometry. Section 5 concludes our discussion of the planar system where we consider the continuum $(N \to \infty)$ limit of the relations. We then turn our attention to non-planar geometries for which the stiffness-matrix formalism has not yet been fully developed. Nevertheless we show that for Landau-type models of inhomogeneous fluids in cylindrical and spherical symmetries it is possible to define analogous matrix elements $S_{\mu\nu}$ which satisfy the same algebraic relations as those in the planar geometry.

We conclude our article with a summary of our main results and make some remarks about other types of variational model.

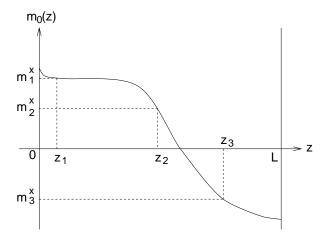


Figure 1. A schematic illustration of the equilibrium profile $m_0(z)$ for a thin-film geometry. The equilibrium positions of surfaces of fixed magnetization m_1^X , m_2^X and m_3^X are shown.

2. Correlation function relations

2.1. Constrained functionals

Consider a fluid confined between two planar walls (of infinite transverse area A) situated in the planes z=0 and z=L. We consider the most general situation in which the

walls are not identical and make no assumption about the preferential adsorption at each surface. Now consider an ordered arrangement of N planes (labelled by $\alpha = 1, ..., N$) corresponding to positions $z_1, z_2, ..., z_N$, and denote the equilibrium magnetization as

$$m_0(z_\alpha) = m_\alpha^X \tag{2.1}$$

at each (see figure 1). We next introduce a constrained minimization of the functional $\Omega[m(r)]$ which may be viewed as a variational prescription for integrating out degrees of freedom except for those infinitesimally close to the planes. To this end suppose that $\Omega[m]$ is minimized subject to the condition that the surfaces described by the position variables $\ell_{\alpha}(y)$ are contours of fixed magnetization m_{α}^{X} :

$$m(\ell_{\alpha}(y)) = m_{\alpha}^{X} \qquad \forall \alpha.$$
 (2.2)

Thus we define a constrained functional [14]

$$H_N[\{\ell_{\alpha}(y)\}; \{z_{\alpha}\}] = \overline{\min} \Omega[m(r)]$$
(2.3)

where the bar denotes the crossing criterion constraint (2.2). By construction, the equilibrium position of the surfaces of fixed magnetization m_{α}^{X} is z_{α} (see (2.1)) and setting $\ell_{\alpha}(y) = z_{\alpha}$ in (2.3) recovers the thermodynamic potential Ω . To make connection with the correlation functions we need to consider the properties of the constrained functional in the vicinity of the global minimum. To this end we suppose that for small translations and fluctuations we may write [12]

$$H_N[\{\ell_{\alpha}(\boldsymbol{y})\}; \{z_{\alpha}\}] = \int d\boldsymbol{y} \left[\frac{1}{2} \Sigma_{\mu\nu}(\{\ell_{\alpha}\}; \{z_{\alpha}\}) \boldsymbol{\nabla} \ell_{\mu} \cdot \boldsymbol{\nabla} \ell_{\nu} + W_N(\{\ell_{\alpha}\}; \{z_{\alpha}\})\right]$$
(2.4)

where the $\Sigma_{\mu\nu}$ constitute the elements of the stiffness matrix Σ for this particular choice of $\{m_{\alpha}^X\}$ (or equivalently $\{z_{\alpha}\}$, see (2.1)). In writing (2.4) we have (for convenience) omitted to include terms related to the curvatures $\nabla^2 \ell_{\alpha}$ etc which may be accounted for using an appropriate rigidity matrix \mathbf{K} . Also in contrast to the analogous effective-Hamiltonian expressions there is no need to specify the momentum cut-offs for each field. Obviously different choices of the $\{z_{\alpha}\}$ will result in different binding potentials W_N and stiffness matrices Σ . For this reason it is sometimes convenient to speak of a continuous set of functionals $\{H_N(\{\ell_{\alpha}\}; \{z_{\alpha}\})\}$ whose elements are distinguished by the particular choice of $\{z_{\alpha}\}$ or equivalently $\{m_{\alpha}^X\}$. Connection with the correlation function $G(z_1, z_2; q)$ is made with an appropriate finite-dimensional matrix representation of the Ornstein–Zernike integral equation (1.4) [13]. The analogue of the direct correlation function is an $N \times N$ matrix with elements (setting $k_B T = 1$)

$$\bar{C}_{\mu\nu}(\boldsymbol{y}_{12}; \{z_{\alpha}\}) = \left. \frac{\delta^{2} H_{N}(\{\ell_{\alpha}\}; \{z_{\alpha}\})}{\delta \ell_{\mu}(\boldsymbol{y}_{1}) \delta \ell_{\nu}(\boldsymbol{y}_{2})} \right|_{\ell_{\mu} = z_{\mu}}$$
(2.5)

which we Fourier transform to exploit the translational invariance. The wave-vector expansion of the matrix $\mathbf{C}(q; \{z_{\alpha}\})$ is rather elegant:

$$\mathbf{C}(q; \{z_{\alpha}\}) = \mathbf{C}_{0}(\{z_{\alpha}\}) + q^{2} \mathbf{\Sigma}(\{z_{\alpha}\}; \{z_{\alpha}\}) + q^{4} \mathbf{K}(\{z_{\alpha}\}; \{z_{\alpha}\}) + \cdots$$
 (2.6)

and is central to the utility of the stiffness-matrix formalism. The zeroth term \mathbf{C}_0 is the matrix of curvatures:

$$\mathbf{C}_{0}(\{z_{\alpha}\}) = \begin{bmatrix} \partial_{11}^{2} & \partial_{12}^{2} & \cdot & \cdot & \partial_{1N} \\ \cdot & \partial_{22}^{2} & \cdot & \cdot & \cdot \\ \partial_{N1}^{2} & \cdot & \cdot & \cdot & \cdot \end{bmatrix} W_{N}(\{\ell_{\alpha}\}; \{z_{\alpha}\})$$
(2.7)

where $\partial_{\mu\nu}^2 = \partial^2/\partial \ell_\mu \, \partial \ell_\nu$ and is evaluated at equilibrium, $\ell_\alpha = z_\alpha$. The correlation function $G(z_\mu, z_\nu; q)$ then follows as [12, 13]

$$G(z_{\mu}, z_{\nu}; q) = m'_{0}(z_{\mu})m'_{0}(z_{\nu})S_{\mu\nu}(q; \{z_{\alpha}\})$$
(2.8)

where the $S_{\mu\nu}$ are the elements of the (symmetric) structure factor matrix satisfying

$$\mathbf{S}(q; \{z_{\alpha}\})\mathbf{C}(q; \{z_{\alpha}\}) = \mathbf{I} \tag{2.9}$$

with I the identity matrix. These equations have previously been used to study meanfield correlation functions at wetting transitions [13]. In that context the $H_N(\{\ell_\alpha\}; \{z_\alpha\})$, correspond to coupled effective Hamiltonians, and the minimization condition arises as a saddle-point approximation to a functional integral. Here we emphasize that the formulation is an *exact* prescription for calculating correlation functions provided that one begins with the appropriate variational functional.

2.2. Local functionals

To begin consider the zeroth moment $G_0(z_\mu, z_\nu)$ for which we only need the binding potential. In order to derive the correlation function relations it is sufficient to consider the properties of 'three-field' functionals $H_3[\ell_1, \ell_2, \ell_3]$, as working with N > 3 does not give any new results. The essential observation leading to the correlation function relations is that due to the local character of the grand potential functional (1.11) the binding potentials necessarily have a separable form (see appendix A):

$$W_3(\{\ell_{\alpha}(\boldsymbol{y})\};\{z_{\alpha}\}) = V_1(\ell_1;\{z_{\alpha}\}) + V_2(\ell_2 - \ell_1;\{z_{\alpha}\}) + V_3(\ell_3 - \ell_2;\{z_{\alpha}\}) + V_4(\ell_3;\{z_{\alpha}\})$$
(2.10)

where the functions V_i depend on the particular choice of variational model and may be considered unknowns. From (2.7) it is a trivial exercise to calculate the matrix $\mathbf{C}_0(\{z_\alpha\})$ and note the following general properties:

$$C_{13}(0; \{z_{\alpha}\}) = 0 \tag{2.11}$$

$$C_{12}(0; \{z_{\alpha}\}) + C_{22}(0; \{z_{\alpha}\}) + C_{23}(0; \{z_{\alpha}\}) = 0.$$
 (2.12)

In turn these impose conditions, via (2.9), on the structure factor matrices $S(0; \{z_{\alpha}\})$ (hereafter we drop the explicit $\{z_{\alpha}\}$ -dependence):

$$\begin{vmatrix} S_{12}(0) & S_{13}(0) \\ S_{22}(0) & S_{23}(0) \end{vmatrix} = 0 {(2.13)}$$

and

$$\begin{vmatrix} S_{12}(0) & S_{23}(0) \\ S_{13}(0) & S_{33}(0) \end{vmatrix} + \begin{vmatrix} S_{11}(0) & S_{12}(0) \\ S_{13}(0) & S_{23}(0) \end{vmatrix} = \begin{vmatrix} S_{11}(0) & S_{13}(0) \\ S_{13}(0) & S_{33}(0) \end{vmatrix}.$$
 (2.14)

For $q \neq 0$ it is necessary to consider the properties of the stiffness matrix and rigidity etc appearing in the expansion (2.6). Nevertheless because of the local character of $\Omega[m]$, variation of $\ell_1(y)$, say, does not affect the constrained magnetization in the region $z \geqslant \ell_2(y)$ (see appendix A). Consequently the Σ_{13} element of the stiffness matrix vanishes (as does K_{13} , the corresponding element in the rigidity matrix), leading to

$$C_{13}(q;\{z_{\alpha}\}) = 0 \qquad \forall q \tag{2.15}$$

which is clearly the generalization of (2.11) and leads to the first of our identities:

$$S_{12}(q)S_{23}(q) = S_{22}(q)S_{13}(q) (2.16)$$

consistent with (2.13) when q = 0. The second identity is restricted to q = 0 and is given in (2.14) above. This may be profitably rewritten as

$$[S_{11}(0) - S_{12}(0)][S_{33}(0) - S_{23}(0)] = [S_{13}(0) - S_{12}(0)][S_{13}(0) - S_{23}(0)].$$
 (2.17)

If we were to consider an *N*-field constrained functional $H_N[\{\ell_{\alpha}\}; \{z_{\alpha}\}]$, the $S_{\mu\nu}(q)$ are related by the same relations applied to any ordered triplet of planes located at $z_{\alpha} \leqslant z_{\beta} \leqslant z_{\gamma}$, i.e.

$$S_{\alpha\beta}(q)S_{\beta\gamma}(q) = S_{\beta\beta}(q)S_{\alpha\gamma}(q) \tag{2.18}$$

and

$$\left[S_{\alpha\alpha}(0) - S_{\alpha\beta}(0)\right] \left[S_{\gamma\gamma}(0) - S_{\beta\gamma}(0)\right] = \left[S_{\alpha\gamma}(0) - S_{\alpha\beta}(0)\right] \left[S_{\alpha\gamma}(0) - S_{\beta\gamma}(0)\right]. \tag{2.19}$$

Clearly (2.18) and (2.19) define an algebra satisfied by the N(N+1)/2 quantities $S_{\mu\nu}(q)$ (for each q). In terms of the pair correlation function $G(z_{\mu}, z_{\nu}; q)$ they read

$$G(z_1, z_2; q)G(z_2, z_3; q) = G(z_2, z_2; q)G(z_1, z_3; q)$$
(2.20)

and

$$\frac{m'_0(z_2)G_0(z_1, z_1) - m'_0(z_1)G_0(z_1, z_2)}{m'_0(z_2)G_0(z_1, z_3) - m'_0(z_3)G_0(z_1, z_2)} = \frac{m'_0(z_2)G_0(z_1, z_3) - m'_0(z_1)G_0(z_2, z_3)}{m'_0(z_2)G_0(z_3, z_3) - m'_0(z_3)G_0(z_2, z_3)}$$
(2.21)

for all $0 \le z_1 \le z_2 \le z_3 \le L$. We emphasize that these relations are valid for all local variational models of the form (1.11). As we shall see, taken together they restrict the form of the zeroth moment $G_0(z_1, z_2)$ and allow us to derive elegant expressions relating G_0 to the force of solvation $f_s(L)$. Before we do this we consider the case of fluid adsorption at a single wall for which the algebra (2.18) and (2.19) has a trivial solution.

3. A simple case: fluid adsorption at a single wall

We wish to show how for a semi-infinite system the algebra conditions, (2.18) and (2.19), with q=0 are met. To this end we only need to consider the properties of the binding potential $W_N(\{\ell_\mu\})$. For later purposes it is convenient to position the wall in the plane $z=z_0$ (fixed). Clearly the equilibrium profile $m_0(z;z_0)$ is a function of $z-z_0$ only, so the partial derivatives satisfy $\partial_z m_0(z;z_0) = -\partial_{z_0} m(z;z_0)$. Due to the local character of the grand potential function the N-field binding potential may be written as

$$W_N(\{\ell_\mu\}) = V_1(\ell_1) + V_2(\ell_2 - \ell_1) + V_3(\ell_3 - \ell_2) + \dots + V_N(\ell_N - \ell_{N-1}). \tag{3.1}$$

The simplifying feature here (compared to the parallel-plate geometry) is that the final collective coordinate $\ell_N(y)$ only enters through one (unspecified) partial binding potential function $V_N(x)$. The curvature matrix has the tridiagonal form

$$\mathbf{C}_{0} = \begin{pmatrix} V_{1}'' + V_{2}'' & -V_{2}'' & 0 & 0 & \cdot & \cdot & \cdot & \cdot \\ -V_{2}'' & V_{2}'' + V_{3}'' & -V_{3}'' & 0 & \cdot & \cdot & \cdot & \cdot \\ 0 & -V_{3}'' & V_{3}'' + V_{4}'' & -V_{4}'' & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & -V_{4}'' & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & \cdot & \cdot & \cdot & \cdot & -V_{N-1}'' & 0 \\ \cdot & \cdot & \cdot & \cdot & \cdot & -V_{N-1}'' & V_{N-1}'' + V_{N}'' & -V_{N}'' \\ \cdot & \cdot & \cdot & \cdot & \cdot & 0 & -V_{N}'' & V_{N}'' \end{pmatrix}$$

$$(3.2)$$

where we have written $V_{\alpha}'' \equiv \partial^2 V_{\alpha}(x)/\partial x^2$ (evaluated at equilibrium $\ell_{\mu} = z_{\mu}$). The inverse matrix \mathbf{S}_0 has a remarkably simple block structure:

$$\mathbf{S}_{0} = \begin{pmatrix} S_{11} & S_{11} & S_{11} & S_{11} & S_{11} & \cdot & \cdot & S_{11} \\ S_{11} & S_{22} & S_{22} & S_{22} & S_{22} & \cdot & \cdot & \cdot \\ S_{11} & S_{22} & S_{33} & S_{33} & S_{33} & \cdot & \cdot & \cdot \\ S_{11} & S_{22} & S_{33} & S_{44} & \cdot & \cdot & \cdot & \cdot \\ \cdot & S_{22} & S_{33} & \cdot & \cdot & \cdot & \cdot & S_{N-2,N-2} \\ \cdot & S_{N-1,N-1} & S_{N-1,N-1} \\ S_{11} & \cdot & \cdot & \cdot & \cdot & \cdot & S_{N-1,N-1} & S_{NN} \end{pmatrix}$$

$$(3.3)$$

with

$$S_{\mu\mu} \equiv S_{\mu\mu}(0) = \sum_{\alpha=1}^{\mu} \frac{1}{V_{\alpha}^{"}}.$$
 (3.4)

The point to notice here is that

$$S_{\mu\nu}(0) = S_{\mu\mu}(0) \qquad \forall \nu \geqslant \mu \tag{3.5}$$

which is indeed a solution of the algebraic conditions (2.18) and (2.19). Thus we are led to the conclusion that within all local variational models of fluid adsorption at a single wall the pair correlation function is of the form

$$G_0(z_1, z_2) = \partial_z m_0(z_1; z_0) \, \partial_z m_0(z_2; z_0) F(\min[z_1, z_2])$$
(3.6)

or equivalently

$$G_0(z_1, z_2) = \partial_{z_0} m_0(z_1; z_0) \, \partial_{z_0} m_0(z_2; z_0) F(\min[z_1, z_2]) \tag{3.7}$$

where F(x) is an unknown function.

This prediction is supported by the explicit Landau theory result for a semi-infinite system (i.e. if we assume that $\mathcal{L}^{(b)}$ is given by (1.12)) which is known to be [12, 13, 18, 19]

$$G_0(z_1, z_2) = m'_0(z_1)m'_0(z_2)\left(\alpha_0 + \int_{z_0}^{\min(z_1, z_2)} \frac{\mathrm{d}z}{m'_0(z)^2}\right)$$
(3.8)

with

$$\alpha_0^{-1} = m_0'(0)[\phi_1''m_0'(0) - m_0''(0)] \tag{3.9}$$

where we have used the abbreviations $m_0'(z) = \partial_z m_0(z; z_0)$ and $\phi_1''(m) = d^2 \phi_1/dm^2$.

Equation (3.5) is also consistent with an exact result due to Henderson and van Swol [20] who have derived an exact statistical mechanical sum rule for fluid adsorption at a pure hard wall, i.e. an external potential:

$$V_{HW}(z) = \begin{cases} \infty & \text{for } z < 0\\ 0 & \text{for } z > 0 \end{cases}$$
 (3.10)

which simply confines the fluid to the half-plane $z \ge 0$.

For this case it is possible to show that

$$G_0(0,z) = \rho_0'(z) \qquad \text{for hard walls} \tag{3.11}$$

with $\rho_0(z)$ ($\Leftrightarrow m_0(z)$) the equilibrium local number density. This is in agreement with (3.5) for the special case $z_\mu = 0$, equivalent to

$$G_0(0,z) \propto m_0'(z)$$
 (3.12)

with an unknown constant of proportionality which presumably depends on the choice of surface interaction term $\phi_1(m)$.

While the semi-infinite solution (3.5) is not particularly interesting it does represent the correct $L \to \infty$ limit of the algebra pertinent to fluids confined in parallel-plate geometries. The analysis for this case is much richer and is discussed in the next section.

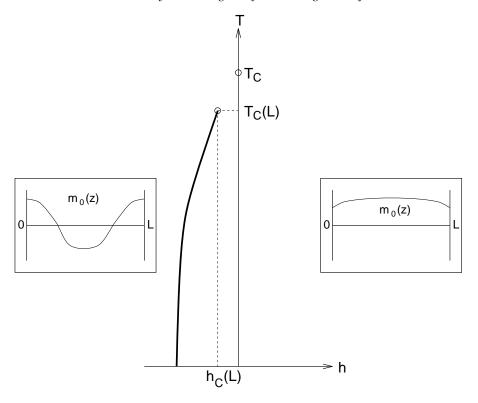


Figure 2. A schematic phase diagram of a thin-film Ising-like magnet with positive surface fields $h_1 = h_2$. Representative magnetization profiles, shown inset, have an even reflection symmetry. The locus of first-order phase transitions (often referred to as capillary condensation) is shifted away from the zero bulk field (h = 0) line. The shifted capillary critical point occurs at $T_C(L)$ and $h_C(L)$.

4. Parallel-plate geometries

4.1. Preliminary remarks

There are two cases in which the correlation function relations (2.18) and (2.19)—with q zero—simplify further and yield elegant expressions for $G_0(z_1, z_2)$. These occur in parallel-plate geometries in which the one-body profile $m_0(z)$ exhibits a simple reflection symmetry. For example if the two walls are identical it necessarily follows that $m_0(z)$ is an *even* function about the plane of symmetry z = L/2. These systems have traditionally attracted the most attention in the literature where the shift of the bulk critical point and first-order phase boundary (capillary condensation) are of interest. The finite-size phase diagram and representative profiles for a typical parallel-plate geometry are shown schematically in figure 2. However, more recently, examples in which the profile exhibits an *odd* reflection symmetry have also drawn considerable interest. Such parities arise in Ising-like systems confined by walls which exert surface fields h_1 and h_2 of equal magnitude but opposite sign on the spins in the z = 0 and z = L planes respectively. The nature of the phase coexistence and criticality in the system is entirely different to that occurring for the case of identical walls. In particular the critical temperature $T_C(L)$ for finite L is determined by length scales associated with wetting [3] and is restricted to lie close to the wetting temperature

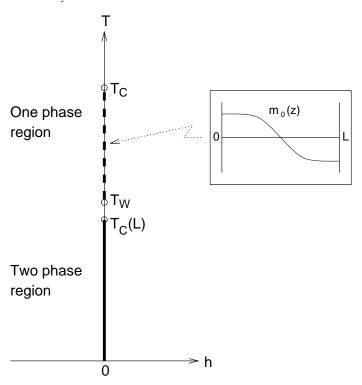


Figure 3. A schematic phase diagram of the thin-film Ising model with opposite surface fields $h_1 = -h_2$. For temperatures $T \geqslant T_C(L)$ (and zero bulk field) the magnetization profiles have an odd reflection symmetry. In the temperature window $T_C \geqslant T \geqslant T_C(L)$ the profile resembles an interface located near the middle of the thin film and characterized by an extremely large interfacial correlation length ξ_{\parallel} . The location of the capillary critical point is determined by length scales pertinent to wetting, and so $T_C(L)$ is less than but close to the critical wetting temperature T_W .

 T_W of the semi-infinite system (see figure 3). For temperatures $T > T_C(L)$ and h = 0 the magnetization profile has the odd symmetry specified above. Of particular interest is the temperature window $T_C > T > T_W$ corresponding to the regime where the finite-size effects have suppressed bulk phase coexistence. The profile $m_0(z)$ for these temperatures resembles an up-spin/down-spin interface situated in the centre of the system. This interface is very weakly pinned by the confining walls and wanders almost freely in the finite-size geometry. The fluctuations associated with this wandering are extremely large, leading to universal scaling behaviour for sufficiently low dimension [4]. We shall return to this in section 4.3 where we use the relations derived in section 4.2 to calculate the singular contribution to the finite-size free energy $\gamma(L)$ (for both even and odd systems).

To begin however, we make some preliminary remarks which will be useful for later purposes and allow us to make contact with other work. To establish our notation we note that the magnetization profile satisfies

$$m_0'(z) = \pm m_0'(L - z) \tag{4.1}$$

for even (-) and odd (+) systems. Moreover we can also impose the additional symmetry requirement

$$G_0(z_1, z_1) = G_0(L - z_1, L - z_1)$$
(4.2)

or equivalently

$$S_{11}(0) = S_{33}(0)$$
 for $z_3 = L - z_1$. (4.3)

Substitution into (2.19) yields the 'sum' rule

$$S_{12}(0) + S_{23}(0) = S_{11}(0) + S_{13}(0)$$
 $z_3 = L - z_1.$ (4.4)

which compares to the 'product' rule (2.18)

$$S_{12}(0)S_{23}(0) = S_{22}(0)S_{13}(0). (4.5)$$

We can therefore anticipate that $S_{12}(0)$ and $S_{23}(0)$ must correspond to the roots of a single quadratic equation (see section 4.2 below). In terms of the zeroth moment itself, equation (4.4) implies

$$\frac{G_0(z_1, z_2) \pm G_0(z_2, L - z_1)}{G_0(z_1, z_1) \pm G_0(z_1, L - z_1)} = \frac{m'_0(z_2)}{m'_0(z_1)}$$
(4.6)

for even (-) and odd (+) systems and $z_1 \le z_2 \le L - z_1$. Further insight follows if we set $z_1 = 0$ to find

$$G_0(0,z) \pm G_0(z,L) = cm_0'(z) \tag{4.7}$$

where c is an unknown constant (which may depend on T, L, h, ...). Note that the equilibrium magnetization profile is also a function of these variables.

It should be emphasized at this stage that this elegant relation follows as a necessary consequence of the local nature of the underlying variational model (1.11). It is therefore encouraging to note that again it is consistent with an *exact* result due to Henderson [15] who has considered statistical mechanical sum rules for a fluid with *arbitrary* intermolecular forces confined between two identical hard walls (i.e. *even* symmetry). Henderson supposed that the external potential could be written as a sum of two semi-infinite wall contributions:

$$V_{\text{ext}}(z) = V_{\infty}(z) + V_{\infty}(L - z) \tag{4.8}$$

and derived a number of exact relations between integrals over $G_0(z_1, z_2)$ and one-body/thermodynamic quantities. For the specific case of hard walls $V_{\infty} = V_{HW}$, these simplify and in particular yield

$$G_0(0, z) - G_0(z, L) = \rho'_0(z)$$
 for hard walls (4.9)

with $\rho_0(z)$ ($\Leftrightarrow m_0(z)$) the equilibrium (local) number density. Clearly this is in agreement with our prediction (4.7) and identifies the unknown constant c as the universal value $c_{HW} = 1$, for hard walls (3.10). Henderson [15] also derives a relation between the pair correlation function and the free energy for this system (recall that we have set $k_b T = 1$):

$$-\frac{\mathrm{d}^2 \gamma}{\mathrm{d}L^2} = G_0(0, L) \qquad \text{for hard walls.} \tag{4.10}$$

In the next section we show how this (and more) can be derived from the correlation function algebra for more general wall potentials.

4.2. The connection with the free energy

For q=0 there are two identities satisfied by the $S_{\mu\nu}(0)$ at any three planes $z_1 \leqslant z_2 \leqslant z_3$ valid for arbitrary (short-ranged) wall interactions ϕ_1 and ϕ_2 . To develop the theory further beyond the elementary remarks made above, it is necessary to inquire what restrictions these conditions impose on the structure of $S_{\mu\nu}(0)$. Consider for example (2.18), with q=0. In

order that this is satisfied for arbitrary choices of z_1 , z_2 and z_3 it follows that the structure factor must have the form of an *ordered* product:

$$S_{\mu\nu}(0) = y^{-}(z_{\mu})y^{+}(z_{\nu}) \qquad \text{for } z_{\mu} \leqslant z_{\nu}$$
 (4.11)

regardless of whether the profile $m_0(z)$ exhibits a reflection symmetry or not. Here $y^-(z)$ and $y^+(z)$ are unknown functions, the properties of which we need to determine. Note that the ordering condition $z_{\mu} \leq z_{\nu}$ is of some importance here and is less restrictive than the assertion that $S_{\mu\nu}(0)$ is a separable function of z_{μ} and z_{ν} . While it is clear that similar remarks also apply for $q \neq 0$, we do not have a second relation which yields valuable information about $y^-(z)$ and $y^+(z)$. To proceed we substitute (4.11) into (2.19) to find

$$y^{+}(z_{1})y^{-}(z_{3}) - y^{+}(z_{1})y^{-}(z_{2}) - y^{+}(z_{2})y^{-}(z_{3})$$

$$= y^{+}(z_{3})y^{-}(z_{1}) - y^{-}(z_{2})y^{+}(z_{3}) - y^{+}(z_{2})y^{-}(z_{1})$$
(4.12)

which can be differentiated with respect to z_2 yielding

$$y^{+}(z_{2})' = \left(\frac{y^{+}(z_{3}) - y^{+}(z_{1})}{y^{-}(z_{3}) - y^{-}(z_{1})}\right)y^{-}(z_{2})' \qquad \forall z_{1}, z_{3} \qquad \Rightarrow y^{-}(z_{2})' = \beta y^{+}(z_{2})'$$
(4.13)

for constant β . This relation is valid for all z_2 and can be integrated to show that $y^-(z)$ and $y^+(z)$ are linearly related:

$$y^{+}(z) = \alpha + \beta y^{-}(z)$$
 (4.14)

with α the constant of integration. By using (4.11) and (4.14), we can solve for $y^-(z_\mu)$, say, in terms of $S_{\mu\mu}(0)$ and then use (4.11) again to yield an expression for $S_{\mu\nu}(0)$. We find

$$KS_{\mu\nu}(0) = (1 \pm \sqrt{1 - KS_{\mu\mu}(0)})(1 \pm \sqrt{1 - KS_{\nu\nu}(0)}) \tag{4.15}$$

where $K = -4\beta/\alpha^2$ is a single undetermined constant. The \pm signs do *not* correspond to the odd/even reflection symmetries mentioned in section 4.1 since we have not yet specialized to these systems. Instead they refer to the positions of z_{μ} and z_{ν} relative to the maximum of $G_0(z,z)$, as we shall see below.

Before we turn to odd/even systems, for which we can explicitly calculate the constant K, we note that the general solution (4.15) is consistent with remarks made earlier concerning the semi-infinite limit. The algebra for this case corresponds to the $K \to 0$ limit of (4.15), with the appropriate choice of signs:

$$\lim_{K \to 0} S_{\mu\nu}(0) = \lim_{K \to 0} \frac{(1 - \sqrt{1 - K S_{\mu\mu}(0)})(1 + \sqrt{1 + K S_{\nu\nu}(0)})}{K} = S_{\mu\mu}(0)$$
(4.16)

as indicated in (3.5).

Hereafter we specialize to odd (+) and even (-) systems. Rearranging (4.15) and using the results of section 4.1 it is straightforward to derive

$$K_{\pm} = \frac{\pm 4G_0(0, L)m_0'(0)^2}{(G_0(0, 0) \pm G_0(0, L))^2}.$$
(4.17)

However, it is also possible to relate K_{\pm} to the excess free energy $\gamma(L)$. We simply quote the result and refer the interested reader to appendix B for the details:

$$K_{\pm} = 4 \frac{\mathrm{d}^2 \gamma(L)}{\mathrm{d}L^2}.$$
 (4.18)

For odd-symmetric systems it is also straightforward to derive

$$K_{+} = \frac{m_0'(L/2)^2}{G_0(L/2, L/2)} \tag{4.19}$$

which is particularly useful. Note that the right-hand side of this relation can be identified as the reciprocal of the maximum value of $S_{\mu\mu}(0)$ as a function of z_{μ} . In fact, using (4.11) and (4.14) to write $S_{\mu\mu}(0)$, and assuming analyticity at all points (true for odd systems only), simple differentiation with respect to z_{μ} shows the maximum value to be $S_{\mu\mu}(0) = -\alpha^2/4\beta$, which is just 1/K.

Thus we have established the following relationship between the correlation function and excess free energy:

$$\frac{\mathrm{d}^2 \gamma}{\mathrm{d}L^2} = \pm \frac{G_0(0, L)m_0'(0)^2}{[G_0(0, 0) \pm G_0(0, L)]^2} \tag{4.20}$$

which is once again (remembering (4.7)) consistent with Henderson's exact results (4.9) and (4.10) for fluids confined between hard walls (3.10).

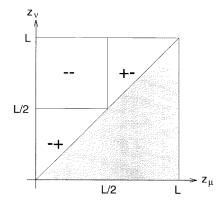


Figure 4. The choice of the signs appearing in the first and second parentheses in equation (4.24).

In this way we are led to a very elegant universal equation relating suitably scaled moments of the correlation function. Specifically, define the *dimensionless* quantities

$$\sigma_{\mu\nu} \equiv \frac{4}{k_B T} \frac{d^2 \gamma}{dL^2} \frac{G_0(z_\mu, z_\nu)}{m'_0(z_\mu) m'_0(z_\nu)}$$
(4.21)

where for completeness we have reinstated the Boltzmann factor. For both odd and even systems the value of these variables at any two planes z_{μ} and z_{ν} ($\geqslant z_{\mu}$) are related by

$$\sigma_{\mu\nu} = (1 \pm \sqrt{1 - \sigma_{\mu\mu}})(1 \pm \sqrt{1 - \sigma_{\nu\nu}})$$
 (4.22)

where the \pm signs must be chosen appropriately (see figure 4). It is a straightforward exercise to check that this result for $\sigma_{\mu\nu}$ is consistent with the algebraic relations

$$\sigma_{12}\sigma_{23} = \sigma_{22}\sigma_{13} \tag{4.23}$$

$$(\sigma_{11} - \sigma_{12})(\sigma_{33} - \sigma_{23}) = (\sigma_{13} - \sigma_{12})(\sigma_{13} - \sigma_{23}) \tag{4.24}$$

for $z_1 \leqslant z_2 \leqslant z_3$.

Making note of the sign of K_{\pm} we see that even and odd systems are distinguished by the ranges of values of the $\sigma_{\mu\nu}$ -variables. In particular

$$0 \leqslant \sigma_{\mu\nu} \leqslant 1$$
 for odd systems (4.25)

with $\sigma_{\mu\mu} = 1$ for $z_{\mu} = L/2$. On the other hand in even systems where the force of solvation $f_s(L)$ between the plates is attractive we have

$$\sigma_{\mu\mu} \leqslant 0$$
 for even systems (4.26)

and this is not bounded from below. Note that $\sigma_{\mu\mu} \to -\infty$ as $z_{\mu} \to L/2$ due to the turning point in the even equilibrium magnetization profile (see figure 2). For both even and odd systems the variables $\sigma_{\mu\nu}$ and $\sigma_{\mu\mu}$ approach zero when $L \to \infty$ (for fixed temperature T) consistent with the semi-infinite limit $K_{\pm} \to 0$ mentioned earlier.

Equations (4.17)–(4.22) are the main results of this paper and are obeyed by all *local* variational models. In the next section we shall demonstrate how they may be used to derive non-trivial scaling expressions for the fluctuation contribution to the free energy $\gamma(L)$.

4.3. Scaling of the finite-size free energy

There are three different scenarios involving fluids confined in parallel-plate geometries for which the free energy $\gamma(L)$ may be expected to exhibit singular, non-analytic behaviour arising from fluctuation-related effects. These are considered separately below.

4.3.1. Odd and even systems at bulk criticality. Exactly at the bulk critical point $T = T_C$ and h = 0, the correlation length in the finite-size system is only limited by the width L. This implies long-ranged (i.e. algebraic) behaviour in the finite-size free energy $\gamma(L)$ which may be likened to the Casimir effect in quantum field theory [21]. The required non-classical (i.e. non-mean-field) scaling of $\gamma(L)$ may be derived from our equations in a number of ways. Perhaps the most elegant is to assert that due to the universal character (i.e. temperature and bulk field *independence*) of the scaled correlation function relation (4.22), the variables $\sigma_{\mu\nu}$ must exhibit finite-size scaling of the form

$$\sigma_{\mu\nu} \approx \Xi^{\pm} \left(\frac{z_{\mu}}{L}, \frac{z_{\nu}}{L} \right)$$
 at $T = T_C$ (4.27)

where the scaling functions $\Xi^{\pm}(x, y)$ are universal [21] for all odd (+) and even (-) systems (restricting our attention to surface fields $h_1 = \pm h_2$ (>0) and positive surface enhancement). This hypothesis may be compared with the definitions (4.21) involving the free energy. Standard finite-size arguments dictate that sufficiently far away from the wall the correlation function and magnetization profile behave (exactly at criticality) as [1, 2, 21]

$$G_0(z_1, z_2) \approx L^{\gamma/\nu - 1} g^{\pm} \left(\frac{z_1}{L}, \frac{z_2}{L}\right)$$
 (4.28)

and

$$m_0(z) \approx L^{-\beta/\nu} \Lambda^{\pm} \left(\frac{z}{L}\right)$$
 (4.29)

where g and Λ are appropriate scaling functions, and γ , ν and β are standard bulk critical exponents. Combining these with (4.21), (4.27) yields

$$\gamma(L) \sim L^{1-(2-\alpha)/\nu} \qquad \text{at } T = T_C \tag{4.30}$$

where we have used the Rushbrooke relation $2-\alpha=2\beta+\gamma$. Thus for d>4 we expect $\gamma(L)\sim L^{-3}$ while for d<4 we find $\gamma(L)\sim L^{-(d-1)}$ on invoking hyperscaling. This is precisely the predicted scaling behaviour of the surface excess free energy [1, 2, 21] and serves to illustrate the generality of the relations derived in section 4.2. While they may be of restricted validity, applicable only to the *local* variational model, they are not necessarily mean-field-like in character.

One may also derive (4.30) using (4.20) which implies

$$\frac{\mathrm{d}^2 \gamma}{\mathrm{d}L^2} \propto G_0(0, L) \qquad \text{as } L \to \infty \tag{4.31}$$

at all temperatures. Using the 'product' relation one has

$$G_0(0,L) = \frac{G_0(0,L/2)^2}{G_0(L/2,L/2)}$$
(4.32)

and it is then straightforward to calculate the L-dependence of the right-hand side of (4.31) at bulk criticality. The denominator follows from (4.28) yielding $G_0(L/2, L/2) \sim L^{\gamma/\nu-1}$. In principle the scaling of $G_0(0, L/2)$ could be calculated from the short-distance expansion (valid for $z_1/L \ll 1$) of (4.28). However, it is easier to use the semi-infinite result $G_0(0,z) \propto m_0'(z)$ quoted in section 3. Combining these with the finite-size scaling of the profile (4.29) it is natural to suppose

$$G_0\left(0, \frac{L}{2}\right) \sim L^{-\beta/\nu + 1}$$
 at $T = T_C$ (4.33)

which recovers $\gamma(L) \sim L^{-(2-\alpha)/\nu+1}$ directly without appealing to the finite-size scaling of $\sigma_{\mu\nu}$.

4.3.2. Odd systems with large interfacial fluctuations. A second example in which the free energy exhibits long-ranged behaviour occurs in odd systems in the temperature window $T_C > T > T_W$ (often referred to as the soft-mode phase [3, 4, 11, 12, 17]). For this case it is most convenient to use (4.18) and (4.19):

$$4\frac{\mathrm{d}^2\gamma}{\mathrm{d}L^2} = \frac{m_0'(L/2)^2}{G_0(L/2, L/2)} \tag{4.34}$$

and recognize that the right-hand side is proportional to ξ_{\parallel}^{-2} , where ξ_{\parallel} is the transverse correlation length characterizing fluctuations in the position of the up-spin/down-spin interface, which wanders 'freely' between the two walls. If we recall that this correlation length shows finite-size scaling such that [4]

$$L \sim \xi_{\parallel}^{\zeta} \tag{4.35}$$

with ζ the roughness exponent, we immediately find

$$\gamma(L) \sim L^{2(1-1/\zeta)}$$
 (4.36)

consistent with the fluctuation theory for confined interfaces [22]. For purely thermal fluctuations for which $\zeta = (3 - d)/2$ for d < 3, this reduces to

$$\gamma(L) \sim L^{-2(d-1)(3-d)}$$
 for $d < 3$ (4.37)

familiar from the theory of wetting [23]. The same expression also follows using arguments similar to those given for the case of $T = T_C$ and this serves to further illustrate the utility of the results (4.17)–(4.22)).

4.3.3. Near the finite-size critical point. Finally we make some remarks on a third possibility which requires further research. For both odd and even geometries it is natural to expect singularities to emerge as we approach the finite-size critical point occurring at $T_C(L)$ and $h = h_C(L)$. Recall that the locations of these critical points is very different for odd and even symmetries (see figure 2 and figure 3). Nevertheless the phase transition occurring at $T_C(L)$ and $h = h_C(L)$ for both these systems is conjectured to belong to the same (d-1)-dimensional bulk Ising universality class [3, 21]. However, an inspection of the well developed mean-field theories shows that the all important free-energy derivative $d^2\gamma/dL^2$ has different singularities for odd and even symmetry. In particular $d^2\gamma/dL^2$ diverges at

the finite-size critical point for an even system [19] but vanishes (as $T_C \to T_C(L)^+$) for an odd symmetry [3]. This would seem to imply a subtle difference between the behaviour of the correlation functions near the respective critical points (by virtue of (4.18) and (4.22))—an observation that is perhaps surprising given, as mentioned above, that the universality classes of the phase transitions are anticipated to be the same for each geometry.

5. Alternative approaches and some generalizations

To end our discussion of planar inhomogeneous fluids we present an alternative derivation of the correlation function relations (2.18) and (2.19) for Landau-type models of the form

$$\Omega[m(r)] = \int dy \int_0^L dz \left\{ \frac{1}{2} (\nabla m)^2 + \phi(m) + \delta(z)\phi_1(m) + \delta(z - L)\phi_2(m) \right\}$$
 (5.1)

by partial solution of the Ornstein–Zernike equation (1.7)—a complete solution not being required. Here we emphasize the properties of a kernel or propagator-like function which also emerges by considering the continuum limit of the algebraic relation (2.18) (see section 5.2). Finally we demonstrate that the same algebraic relations amongst the (suitably redefined) $S_{\mu\nu}$ are also obeyed for non-planar inhomogeneous fluids exhibiting a cylindrical or spherical symmetry.

5.1. The kernel function for the Ornstein–Zernike equation

For the Landau model (5.1) the Ornstein–Zernike equation reduces to [6, 7]

$$[\hat{\mathcal{L}}(z_2) + q^2]G(z_1, z_2; q) = \delta(z_2 - z_1)$$
(5.2)

where the second-order linear operator $\hat{\mathcal{L}}$ is

$$\hat{\mathcal{L}}(z) = -\frac{\partial^2}{\partial z^2} + \phi''(m_0(z)). \tag{5.3}$$

The same operator appears in the differential equation for the profile $m_0(z)$ which may be written as

$$\hat{\mathcal{L}}(z)m_0'(z) = 0 \tag{5.4}$$

and will be required later. To proceed we first define the function

$$\mathcal{K}(z_1, z_2; \mathbf{q}) = \frac{\partial}{\partial z_2} \log G(z_1, z_2; \mathbf{q})$$
(5.5)

which from (5.2) satisfies the non-linear equation (for $z_1 \neq z_2$)

$$\frac{d\mathcal{K}}{dz_2} = \phi''(m(z_2)) + q^2 - \mathcal{K}^2.$$
 (5.6)

Assuming that (5.6) has a family of solutions $k(z_2, \mathbf{q}; a)$, parameterized by a, then

$$\mathcal{K}(z_1, z_2; \mathbf{q}) = \begin{cases} k(z_2, \mathbf{q}; a_1) & \text{for } z_2 > z_1 \\ k(z_2, \mathbf{q}; a_2) & \text{for } z_2 < z_1 \end{cases}$$
(5.7)

and the δ -function in (5.2) implies the boundary condition

$$k(z_1, \mathbf{q}; a_1) - k(z_1, \mathbf{q}; a_2) = -\frac{1}{G(z_1, z_1; \mathbf{q})}.$$
(5.8)

Without loss of generality this can be considered an equation for a_2 , and implies that $a_2 = a_2(z_1, \mathbf{q})$. Consequently,

$$\mathcal{K}(z_1, z_2; \mathbf{q}) = \mathcal{K}(z_2; \mathbf{q}) \qquad \text{for } z_1 \leqslant z_2. \tag{5.9}$$

As we shall see, the existence of K is central to the derivation of the correlation function relations. Integrating (5.5) and remembering (5.9) we find

$$G(z_1, L; \mathbf{q}) - G(z_1, z_2; \mathbf{q}) = \int_{z_2}^{L} dz' \, \mathcal{K}(z'; \mathbf{q}) G(z', z_1; \mathbf{q}) \qquad \text{for } z_1 < z_2.$$
 (5.10)

This becomes in real space (via the convolution theorem)

$$G(\mathbf{r}_1, \mathbf{r}_2) = G(\mathbf{r}_1, (\mathbf{y}_2, L)) + \int d\mathbf{r}' \ G(\mathbf{r}_1, \mathbf{r}') K^{-}(\mathbf{r}', \mathbf{r}_2) \qquad \text{for } z_1 < z_2$$
 (5.11)

where K^- can be thought of as an advanced propagator:

$$K^{-}(\mathbf{r}', \mathbf{r}_{2}) \equiv -\theta(z' - z_{2})K(z'; \mathbf{y}_{2} - \mathbf{y}'). \tag{5.12}$$

Here K(z; y) is the Fourier transform of the kernel K(z; q). In this way it is possible to interpret the correlation function at positions r_1 and r_2 (say) in a standard way; i.e. making an analogy between position z and time, $G(r_1, r')$ at early 'time' $z = z_1$ can be propagated to later time $z = z_2$ making use of information from the 'future' $(z' > z_2)$ only.

The 'product' rule follows directly from the integral relation (found from equations (5.5) and (5.9))

$$G(z_1, b; \mathbf{q}) = G(z_1, a; \mathbf{q}) \exp\left[\int_a^b dz \ \mathcal{K}(z; \mathbf{q})\right]$$
(5.13)

valid for all $b \ge a \ge z_1$. Setting $z_1 = a$ and choosing c satisfying $a \le c \le b$ we can write

$$G(a, b; \mathbf{q}) = G(a, a; \mathbf{q}) \exp\left[\int_{a}^{b} dz \, \mathcal{K}(z; \mathbf{q})\right]$$

$$= G(a, a; \mathbf{q}) \exp\left[\int_{a}^{c} dz \, \mathcal{K}(z; \mathbf{q})\right] \exp\left[\int_{c}^{b} dz \, \mathcal{K}(z; \mathbf{q})\right]$$

$$= G(a, a; \mathbf{q}) \frac{G(a, c; \mathbf{q})}{G(a, a; \mathbf{q})} \frac{G(b, c; \mathbf{q})}{G(c, c; \mathbf{q})}$$
(5.14)

where we have used (5.13) extensively. The final equation is nothing more than (2.18).

The second correlation function relation can be found from the explicit solution of (5.6) when q = 0:

$$\mathcal{K}_0 = \frac{\mathrm{d}}{\mathrm{d}z} \left[\log Y(z) \right] \tag{5.15}$$

where $d^2Y/dz^2 = \phi''(m_0(z))Y(z)$. From the definition (5.5) one finds (for $z_2, z_3 \ge z_1$)

$$\frac{G_0(z_1, z_2)}{G_0(z_1, z_3)} = \frac{Y(z_2)}{Y(z_3)} \Rightarrow G_0(z_1, z_2) = Y(z_2)X(z_1)$$
(5.16)

for some function X(z). Enforcing the Ornstein–Zernike conditions

$$\hat{\mathcal{L}}(z_1)G_0(z_1, z_2) = \hat{\mathcal{L}}(z_2)G_0(z_1, z_2) = \delta(z_1 - z_2)$$
(5.17)

we see that the functions X and Y are related by

$$X(z) = \alpha Y(z) + \beta m_0'(z) \tag{5.18}$$

for constant α and β , due to the linear nature of the operator $\hat{\mathcal{L}}(z)$ and (5.4). This is precisely equivalent to the linear relation (4.14) which we deduced as a necessary consequence of the second correlation function identity (2.19).

5.2. The continuum limit

The propagator approach also emerges from the more general stiffness-matrix formalism by taking the continuum limit of (2.18). Consider two boundary planes located at z = a and z = b (with a < b) and divide the region between them by n other planes separated by a constant distance h. Combining 'product' rules (2.18) defined for each consecutive set of two planes and the boundary at z = b one finds

$$G(a,b;q) = \frac{G(a,z_1;q)G(z_1,z_2;q)\cdots G(z_n,b;q)}{G(z_1,z_1;q)G(z_2,z_2;q)\cdots G(z_n,z_n;q)}.$$
(5.19)

Setting $z_0 = a$ and $z_{n+1} = b$, equation (5.19) can be rewritten as

$$\frac{G(a,b;q)}{G(a,a;q)} = \prod_{i=0}^{i=n} G(z_i, z_i + h; q) / \prod_{i=0}^{i=n} G(z_i, z_i; q)
= \exp \left[\sum_{i=0}^{n} \{ \log G(z_i, z_i + h; q) - \log G(z_i, z_i; q) \} \right]
= \exp \left[\sum_{i=0}^{n} h \left\{ \frac{\log G(z_i, z_i + h; q) - \log G(z_i, z_i; q)}{h} \right\} \right].$$
(5.20)

Taking the continuum limit $h \to 0$, $n \to \infty$ we find that

$$G(a, b; q) = U(a, b; q)G(a, a; q)$$
 for $a < b$ (5.21)

where

$$U(a, b; q) \equiv \exp\left[\int_{a}^{b} dz \, \mathcal{K}(z; q)\right]$$
 (5.22)

and $\mathcal{K}(z;q)$ is some unknown function. For an infinitesimal displacement dz_2 ,

$$U(z_{1}, z_{2} + dz_{2}; \mathbf{q}) = \exp\left[\int_{z_{1}}^{z_{2}+dz_{2}} dz \, \mathcal{K}(z; \mathbf{q})\right] \simeq \exp[\mathcal{K}(z_{2}; \mathbf{q}) \, dz_{2}]U(z_{1}, z_{2}; \mathbf{q})$$

$$\simeq [1 + \mathcal{K}(z_{2}; \mathbf{q}) \, dz_{2}]U(z_{1}, z_{2}; \mathbf{q})$$
(5.23)

which implies

$$\frac{U(z_1, z_2 + dz_2) - U(z_1, z_2)}{dz_2} = \mathcal{K}(z_2; \mathbf{q}) U(z_1, z_2; \mathbf{q})
\Rightarrow \frac{\partial}{\partial z_2} U(z_1, z_2; \mathbf{q}) = \mathcal{K}(z_2; \mathbf{q}) U(z_1, z_2; \mathbf{q})$$
(5.24)

taking the limit $dz_2 \rightarrow 0$. It is intriguing that (5.24) is very similar to the Schrödinger equation for the time evolution operator, with the Hamiltonian time dependent but self-commuting at different times [24].

Multiplying (5.24) by $G(z_1, z_1; q)$ and then using (5.21),

$$\frac{\partial}{\partial z_2} U(z_1, z_2; \boldsymbol{q}) G(z_1, z_1; \boldsymbol{q}) = \mathcal{K}(z_2; \boldsymbol{q}) U(z_1, z_2; \boldsymbol{q}) G(z_1, z_1; \boldsymbol{q})$$

$$\Rightarrow \frac{\partial}{\partial z_2} G(z_1, z_2; \boldsymbol{q}) = \mathcal{K}(z_2; \boldsymbol{q}) G(z_1, z_2; \boldsymbol{q})$$
(5.25)

which is equivalent to (5.5) with (5.9), and $\mathcal{K}(z;q)$ is, of course, just the kernel function.

Thus we have shown that (2.18) implies via its continuum limit the existence of a kernel function $\mathcal{K}(z;q)$. In turn the kernel function can be understood as being an advanced propagator for correlation functions in real space.

5.3. Non-planar geometries

The properties of inhomogeneous fluids confined in *non-planar* geometries has also attracted attention in recent years. Perhaps the most important of these is the ease of fluid adsorption in cylindrical systems [25] (as idealized models of porous materials). Despite continued interest we are not aware of any discussion of correlation function structure in such systems, and to complete our article we make some remarks which follow from those made in section 5.1.

Consider then a fluid confined in an infinitely long cylinder $(-\infty < z < \infty)$ of radius R (and connected to an external reservoir of particles). The grand potential density functional is taken to be the Landau-type model equation

$$\Omega[m] = \int_{-\infty}^{\infty} dz \int_{0}^{2\pi} d\phi \int_{0}^{R} r dr \left\{ \frac{1}{2} (\nabla m)^{2} + \phi(m) + \delta(r - R)\phi_{1}(m) \right\}$$
 (5.26)

which is analogous to (5.1). The connected correlation function $G(r_1, r_2)$ only depends on the relative angle $\phi_2 - \phi_1 \equiv \phi_{21}$ and azimuthal distance $z_2 - z_1 \equiv z_{21}$ between the particles as well as the radial distances r_1 and r_2 . To exploit this we first define a 'zeroth' moment analogous to (1.8):

$$G_0(r_1, r_2) = \int_{-\infty}^{\infty} dz_{21} \int_0^{2\pi} d\phi_{21} \ G(r_1, r_2).$$
 (5.27)

The Ornstein-Zernike equation is

$$[\nabla_2^2 + \phi''(m(r_2; R))]G(r_2, r_1) = \delta(r_2 - r_1)$$
(5.28)

where m(r; R) is the equilibrium profile satisfying the Euler-Lagrange equation

$$\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial}{\partial r}\right)m(r;R) = \phi'(m(r;R)) \tag{5.29}$$

together with a boundary condition at r = R. The differential equation for $G(r_1, r_2)$ can be integrated with respect to z_{21} and ϕ_{21} to yield

$$\left[-\frac{1}{r_2} \frac{\partial}{\partial r_2} \left(r_2 \frac{\partial}{\partial r_2} \right) + \phi''(m(r_2; R)) \right] G_0(r_1, r_2) = 0 \qquad \text{for } r_1 \neq r_2$$
 (5.30)

which we need to solve. The point to notice here is that the partial derivative $(\partial m/\partial R)(r; R)$ satisfies the same linear differential equation:

$$\left[-\frac{1}{r_2} \frac{\partial}{\partial r_2} \left(r_2 \frac{\partial}{\partial r_2} \right) + \phi''(m(r_2; R)) \right] \frac{\partial m}{\partial R}(r_2; R) = 0.$$
 (5.31)

As a consequence it is natural to define the 'structure' factor matrix elements as

$$S_{\mu\nu}(0) \equiv G_0(r_{\mu}, r_{\nu}) / \left(\frac{\partial m}{\partial R}(r_{\mu}; R) \frac{\partial m}{\partial R}(r_{\nu}; R) \right)$$
 (5.32)

which, we anticipate, satisfy the same algebraic conditions (2.18) and (2.19) as the planar system. This is borne out by the explicit solution

$$G_0(r_1, r_2) = \frac{\partial m}{\partial R}(r_1; R) \frac{\partial m}{\partial R}(r_2; R) \left(\alpha + \int_{\max(r_1, r_2)}^R dr \ r^{-1} \left(\frac{\partial m}{\partial R} \right)^{-2} \right)$$
 (5.33)

where α is determined by a simple boundary condition. In terms of the structure factors we note that

$$S_{\mu\nu}(0) = S_{\mu\mu}(0) \qquad \forall r_{\nu} \geqslant r_{\mu} \tag{5.34}$$

which is analogous to the semi-infinite solution (3.5) for planar systems. Indeed for fluid adsorption on the outside of a cylinder the Landau theory result is

$$G_0(r_1, r_2) = \frac{\partial m}{\partial R}(r_1; R) \frac{\partial m}{\partial R}(r_2; R) \left(\alpha' + \int_R^{\min(r_1, r_2)} dr \ r^{-1} \left(\frac{\partial m}{\partial R}\right)^{-2}\right)$$
(5.35)

which is precisely of the form (3.8).

It is a simple matter to repeat the analysis for fluid adsorption in spherically symmetric systems (coordinates r, θ, ϕ) where the appropriate zeroth moment is

$$G_0(r_1, r_2) = \int_0^{\pi} \sin(\theta_{12}) d\theta_{12} \int_0^{2\pi} d\phi_{21} G(r_1, r_2)$$
 (5.36)

where $\theta_2 - \theta_1 \equiv \theta_{12}$. In fact, if we restrict our attention to adsorption at a single wall (with $z \leftrightarrow r$ and $z_0 \leftrightarrow R$), or outside cylinders and spheres, the general solution can be written as

$$G_0(r_1, r_2) = \frac{\partial m}{\partial R}(r_1; R) \frac{\partial m}{\partial R}(r_2; R) \left(\text{constant} + \int_R^{\min(r_1, r_2)} dr \ r^{-d'} \left(\frac{\partial m}{\partial R} \right)^{-2} \right)$$
 (5.37)

where d' = 0, 1, 2 for walls, cylinders and spheres respectively. We can interpret d' as the dimension of the boundary surface (two for three-dimensional systems) minus the number of dimensions in which the systems is unbounded. For all of these systems the structure factors satisfy (3.5). For the more general case of thin-film geometries and adsorption between two concentric cylinders or spheres the structure factors can be shown [26] to satisfy the general algebraic conditions (2.18) and (2.19).

6. Conclusions

To complete our article we summarize our main results and make some remarks about possible future work.

(i) The stiffness-matrix formalism for calculating the correlation functions $G(z_{\mu}, z_{\nu}; q)$ in planar inhomogeneous fluids modelled by local variational models naturally leads to two identities relating this function at three arbitrary positions $z_1 \leqslant z_2 \leqslant z_3$. Taken together they restrict the form of the zeroth moment $G_0(z_{\mu}, z_{\nu})$ and allow us to define dimensionless scaled variables

$$\sigma_{\mu\nu} \equiv \frac{4}{k_B T} \frac{d^2 \gamma}{dL^2} \frac{G_0(z_\mu, z_\nu)}{m'_0(z_\mu) m'_0(z_\nu)}$$
(6.1)

for thin-film geometries exhibiting even or odd reflection symmetries. The cross term σ_{12} is solved for explicitly as a universal function of σ_{11} and σ_{22} .

- (ii) For even systems and particular choices of z_1 , z_2 and z_3 , our results are consistent with previously derived exact expressions for fluid adsorption at purely repulsive hard walls [15] with arbitrary fluid–fluid interactions.
- (iii) Using our results we have been able to rederive non-trivial scaling expressions for the long-ranged (power-law) finite-size contribution to the excess free energy $\gamma(L)$ (a) at the bulk critical point, and (b) in the soft-mode phase for a geometry with competing surface fields (odd systems). There is a hint in our analysis that the correlation function may behave somewhat differently near the capillary critical point of odd- and even-symmetric systems.
- (iv) While the correlation function identities may also be derived directly, for Landautype models, by explicit solution of the Ornstein–Zernike equation, it is unlikely that the general character of the relations would have been spotted using this method. This serves

to illustrate the utility of the stiffness-matrix formalism which has been previously used to derive the stiffness-matrix free-energy relation in the theory of wetting [13]. One may add here that while most of our analysis has been restricted to q=0, one may also discuss the structure of higher moments of the correlation function. For example, consider the position-dependent transverse correlation length $\xi_{\parallel}(z_{\mu}, z_{\nu})$, defined via the asymptotic expansion

$$G(z_{\mu}, z_{\nu}; q) = G_0(z_{\mu}, z_{\nu})[1 - \xi_{\parallel}^2(z_{\mu}, z_{\nu})q^2 + O(q^4)] \qquad \text{for } q \to 0.$$
(6.2)

Then, from the 'product' identity (2.18) we immediately derive the elegant correlation length relation

$$\xi_{\parallel}^{2}(z_{1}, z_{2}) + \xi_{\parallel}^{2}(z_{2}, z_{3}) = \xi_{\parallel}^{2}(z_{2}, z_{2}) + \xi_{\parallel}^{2}(z_{1}, z_{3})$$

$$(6.3)$$

for $z_1 \leqslant z_2 \leqslant z_3$. Using this identity and other stiffness-matrix relations it is possible to show [26] that the three correlation lengths $\xi_{\parallel}^2(L/2,L/2), \xi_{\parallel}^2(0,L/2)$ and $\xi_{\parallel}^2(0,L)$ all diverge in precisely the same manner as $L \to \infty$ at $T = T_C$ (even and odd systems) and $T_C > T > T_W$ (odd systems) in zero bulk field.

(v) Finally, we believe that it would be worthwhile developing the stiffness-matrix formalism for other variational functionals; for example, one could consider local models of two or more density variables such as arise in systems with N-component vector order parameters. Within the same framework it would be possible to study local entropy-type functionals $\Omega[m(r), \epsilon(r)]$ of the magnetization and the energy density which have been forwarded recently as better candidates for modelling critical behaviour [10]. A preliminary analysis of these models reveals analogues of the 'product' rule (2.18) although further work is required to find whether the identity (2.19) also generalizes.

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Appendix A. A separable binding potential

Let us denote as $m_{\pi}^{(N)}(z; \{\ell_{\alpha}\})$ the planar profile which minimizes $\Omega[m]$ subject to the crossing constraints (2.2). The binding potential is determined by the relation (dropping the implicit $\{z_{\alpha}\}$ -dependence)

$$W_{N}(\{\ell_{\alpha}\}) = \phi_{1}(m_{\pi}^{(N)}(0; \{\ell_{\alpha}\})) + \phi_{2}(m_{\pi}^{(N)}(L; \{\ell_{\alpha}\}))$$

$$+ \int_{0}^{L} dz \ \mathcal{L}^{(b)}(m_{\pi}^{(N)}(z; \{\ell_{\alpha}\}), \partial_{z}m_{\pi}^{(N)}(z; \{\ell_{\alpha}\}))$$
(A.1)

neglecting constant terms independent of the collective coordinates. This is profitably rewritten:

$$W_{N}(\{\ell_{\alpha}\}) = \phi_{1}(m_{\pi}^{(N)}(0; \{\ell_{\alpha}\})) + \phi_{2}(m_{\pi}^{(N)}(L; \{\ell_{\alpha}\}))$$

$$+ \sum_{n=0}^{N} \int_{\ell_{n}}^{\ell_{n+1}} dz \ \mathcal{L}^{(b)}(m_{\pi}^{(N)}(z; \{\ell_{\alpha}\}), \partial_{z}m_{\pi}^{(N)}(z; \{\ell_{\alpha}\}))$$
(A.2)

where we have defined $\ell_0 = 0$ and $\ell_{N+1} = L$. The profile itself satisfies the second-order Euler–Lagrange equation

$$\frac{\partial}{\partial z} \left(\frac{\partial \mathcal{L}^{(b)}}{\partial (\partial_z m_\pi^{(N)})} \right) = \frac{\partial \mathcal{L}^{(b)}}{\partial m_\pi^{(N)}} \tag{A.3}$$

so for $\ell_{\mu} < z < \ell_{\mu+1}$ the solution is completely determined by the boundary conditions $m_{\pi}^{(N)}(\ell_{\mu};\{\ell_{\alpha}\}) = m_{\mu}^{X}$ and $m_{\pi}^{(N)}(\ell_{\mu+1};\{\ell_{\alpha}\}) = m_{\mu+1}^{X}$. Consequently we can write

$$m_{\pi}^{(N)}(z; \{\ell_{\alpha}\}) = F_{\mu}(z - \ell_{\mu}, \ell_{\mu+1} - \ell_{\mu})$$
 for $\ell_{\mu} \leqslant z \leqslant \ell_{\mu+1}$ (A.4)

for all μ and with F_{μ} some appropriate function which we need not determine. Substituting into (A.2) then yields

$$W_N(\{\ell_\mu\}) = \sum_{n=1}^{N+1} V_n(\ell_n - \ell_{n-1})$$
(A.5)

exhibiting the required separability properties.

Appendix B. The connection with the free energy

Consider odd systems. We start by using (4.7) so that (4.17) can be rewritten as

$$K_{+} = \frac{4}{c^2} G_0(0, L) \tag{B.1}$$

and using (4.7) again (with z = L/2)

$$K_{+} = \frac{G_0(0, L)}{G_0(0, L/2)^2} m_0' \left(\frac{L}{2}\right)^2.$$
(B.2)

However, from the 'product' relation (2.18)

$$G_0\left(0, \frac{L}{2}\right)^2 = G_0(0, L)G_0\left(\frac{L}{2}, \frac{L}{2}\right)$$
 (B.3)

and so

$$K_{+} = \frac{m'_{0}(L/2)^{2}}{G_{0}(L/2, L/2)}$$
(B.4)

which is (4.19). The right-hand side of (B.4) is the inverse of the structure factor matrix element for a surface of fixed magnetization $m^X=0$ (located at the centre of the thin film on average). If we calculate the binding potential $W_1(\ell)$ for a *single* surface of fixed magnetization $m^X=0$ we can identify

$$\gamma(L) = W_1 \left(\frac{L}{2}\right). \tag{B.5}$$

However, from the stiffness-matrix formalism with N=1 we also find

$$\frac{m_0'(L/2)^2}{G_0(L/2, L/2)} = W_1''(\ell)|_{L/2} = 4\frac{\mathrm{d}^2 W_1(L/2)}{\mathrm{d}L^2}$$
(B.6)

valid in the soft-mode phase $T \geqslant T_W$ where z = L/2. This completes the proof.

A similar approach can be used for even systems, and therefore we find generally

$$K_{\pm} = 4 \frac{\mathrm{d}^2 \gamma(L)}{\mathrm{d}L^2}.$$
 (B.7)

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